

## Common Fixed Point Theorems for Generalisation of R-Weak Commutativity

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**Abstract:** The main purpose of this paper is to obtain fixed point theorems for R-weak commutativity which generalizes theorem 1 of R.P.Pant [2].

**Key Words:** and Phrases. Fixed point, coincidence point, compatible maps, non-compatible, R-weak commuting maps.

### I. Introduction

In 1986 Jungck [1] generalized the concept of weakly commuting mappings by introducing the notion of compatible maps. Since then the study of common fixed points of generalized contractions satisfying compatibility or some other commutativity conditions have emerged as an area of research activity. The central question concerning the common fixed points of generalized contractions may be formulated as given the self maps  $A_i, B_i, S_i, T_i \forall i$  of a metric space  $(X, d)$  satisfying a contractive condition what assumptions on commutativity and the contractive condition guarantee the existence of a common fixed point. For compatible maps satisfying the contractive condition.

$$(1) d(A_i x, B_i y) < M_{ii}(x, y) = \max \{ d(S_i x, T_i y), d(A_i x, S_i x), d(B_i y, T_i y), [d(S_i x, B_i y) + d(A_i x, T_i y)]/2 \} \forall i$$

(2)  $d(A_i x, B_i y) \leq \phi (M_{ii}(x, y))$  where  $\phi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is an upper semi-continuous function such that  $\Phi(t) < t$ , for each  $t > 0$ . And (3) there exists a function  $\delta (0, \infty) \rightarrow (0, \infty)$ , which is non decreasing or lower semi-continuous, such that  $\epsilon \leq M_{ii}(x, y) < \epsilon + \delta (\epsilon)$  implies that  $d(A_i x, B_i y) < \epsilon$ .

Key Words and Phrases. Fixed point, coincidence point, compatible maps, non-compatible, R-weak commuting maps.

### II. Preliminaries

Before proving our results, we need the following definitions and known results in this sequel.

**Definition 2.1** ([2]). Two self maps  $A$  and  $S$  of a metric space  $(X, d)$  are called compatible if  $\lim_{n \rightarrow \infty} d(AS_{x_n}, SA_{x_n}) = 0$  whenever  $\{x_n\}$  is a sequence in  $X$  such that  $\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = t$  for some  $t$  in  $X$ .

**Definition 2.2** ([2]). Two self maps  $A$  and  $S$  of a metric space  $(X, d)$  are defined to be R-weakly commuting at a point  $x$  in  $X$  if  $d(AS_x, SA_x) \leq R d(A_x, S_x)$  for some  $R > 0$ . The maps  $A$  and  $S$  are called point wise R-weakly commuting on  $X$  if given  $x$  in  $X$  there exists  $R > 0$  such that  $d(AS_x, SA_x) \leq R d(A_x, S_x)$ .

**Remark 2.3.**

- It is obvious that maps  $A$  and  $S$  are point wise R-weakly commuting on  $X \iff$  they commute at their coincidence points.
- If  $A$  and  $S$  commute at their coincidence, we can define  $R = \max \{1, d(AS_x, SA_x) / d(A_x, S_x)\}$  when  $A_x \neq S_x$ , while  $R$  can be chosen arbitrarily when  $x$  is a coincidence point. The converse of this is obvious. Thus  $A$  and  $S$  can fail to be point wise R-weakly commuting only if they possess a coincidence point at which they do not commute.
- Compatible maps are necessarily point wise R-weakly commuting since compatible maps commute at their coincidence points.

R.P.Pant proved the following theorems.

**Theorem 2.4** (R.P.Pant [1]). Let  $(A, S)$  and  $(B, T)$  be point wise R-weakly commuting pairs of self mappings of a metric space  $(X, d)$  satisfying (i)  $AX \subset TX, BX \subset SX$ ,

(ii)  $d(A_x, B_y) < M(x, y) = \max \{ d(S_x, T_y), d(A_x, S_x), d(B_y, T_y), [d(A_x, T_y) + d(B_y, S_x)]/2 \}$  whenever  $M(x, y) > 0$ . Suppose that one of the pairs  $(A, S)$  or  $(B, T)$  is compatible and the other is Non compatible. If the mapping in the compatible pair be continuous then  $A, B, S$  and  $T$  have a unique common fixed point.

**Theorem 2.5** (R.P.Pant [2]). Let  $\{A_i\}, i=1, 2, 3, \dots$  and  $T$  be self-mappings of a metric space  $(X, d)$  such that  $A_i X \subset SX$  when  $i > 1, A_1 X \subset TX$  and (i) Pairs  $(A_1, S)$  and  $(A_i, T), i > 1$ , are point wise R-weakly commuting with atleast one pair non compatible,

(ii)  $d(A_1x, A_1y) < M_{11}(x, y) = \max \{d(S_x, T_y), d(A_1x, S_x), d(A_1y, T_y), [d(A_1x, T_y) + d(A_1y, S_x)]/2\}$ .

Also let  $\phi : R_+ \rightarrow R_+$  denote a function such that  $\Phi(t) < t$  for each  $t > 0$ . Whenever  $M_{11}(x, y) > 0$  and  $i > 1$ . (iii)

$d(A_1x, A_2y) \leq \phi(M_{12}(x, y))$ . If the range of one of the mappings is a complete subspace of X then all the  $A_i, S$  and  $T \forall i$  have a unique common fixed point.

### III. Main Results

In this section we prove common fixed point theorem for sequence of mappings that generalizes the theorem 2.5.

Theorem 3.1. Let  $\{A_i\}, \{B_i\}, \{S_i\}, \{T_i\} \forall i=1,2,3,\dots$  be self-mappings of a metric space  $(X, d)$  such that  $B_iX \subset S_iX, A_iX \subset T_iX \forall i$  and (i) Pairs  $(A_i, S_i)$  and  $(B_i, T_i) \forall i$  are Point wise R-weakly commuting with atleast one pair non compatible,

(ii)  $d(A_i x, B_i y) < M_{ii}(x, y) = \max \{d(S_i x, T_i y), d(A_i x, S_i x), d(B_i y, T_i y), [d(S_i x, B_i y) + d(A_i x, T_i y)]/2\} \forall i$  whenever  $M_{ii}(x, y) > 0$ . If the range of one of the mappings is a Complete subspace of X then all the  $A_i, B_i, T_i$  and  $S_i \forall i$  have a unique common fixe point.

Proof: Suppose that  $T_i$  is non-compatible with  $B_i \forall i$ .

Then there exists a sequence  $\{z_n\}$  in  $X$  such that  $\lim_{n \rightarrow \infty} B_i z_n = \lim_{n \rightarrow \infty} T_i z_n = t$  for some  $t$  in  $X. \forall i$ . But  $\lim_{n \rightarrow \infty} d(B_i T_i z_n, T_i B_i z_n)$  is either non zero or does not exist. Since,  $B_i X \subset S_i X \forall i$  corresponding to each  $z_n$  there exists  $x_n$  in  $X$  such that  $B_i z_n = S_i x_n \forall i$ . Thus  $B_i z_n = S_i x_n \rightarrow t$  and  $T_i z_n \rightarrow t$  as  $n \rightarrow \infty$ . We claim that  $A_i x_n \rightarrow t$  as  $n \rightarrow \infty$ . If not, then by virtue of (ii) for sufficiently large values of  $n$  we get  $d(A_i x_n, B_i z_n) \leq M_{ii}(x_n, z_n) = \max \{d(S_i x_n, T_i z_n), d(A_i x_n, S_i x_n), d(B_i z_n, T_i z_n), [d(S_i x_n, B_i z_n) + d(A_i x_n, T_i z_n)]/2\} \forall i$ .  
 $= d(A_i x_n, S_i x_n) = d(A_i x_n, B_i z_n)$ . Which is a contradiction.

Hence  $A_i x_n \rightarrow t$ . Also, Since  $A_i X \subset T_i X \forall i$

For each  $x_n$  there exists  $y_n$  in  $X$  such that  $A_i x_n = T_i y_n \forall i$  and  $A_i x_n = T_i y_n \rightarrow t$ .

We show that  $B_i y_n \rightarrow t \forall i$ . If not, then using (ii) for sufficiently large values of  $n$ , we get  $d(A_i x_n, B_i y_n) < M_{ii}(x_n, y_n) = \max \{d(S_i x_n, T_i y_n), d(A_i x_n, S_i x_n), d(B_i y_n, T_i y_n), [d(S_i x_n, B_i y_n) + d(A_i x_n, T_i y_n)]/2\} \forall i$ .

$= d(A_i x_n, B_i y_n) \forall i$  Which is a contradiction. Thus  $A_i x_n \rightarrow t, S_i x_n \rightarrow t, T_i y_n \rightarrow t, B_i y_n \rightarrow t \forall i$  where  $T_i y_n = A_i x_n \forall i$ .

Next, suppose that  $S_i \forall i$  is a noncompatible with  $A_i \forall i$ .

Then there exists a sequence  $\{x_n\}$  in  $X$  such that  $\lim_{n \rightarrow \infty} A_i x_n = \lim_{n \rightarrow \infty} S_i x_n = t$  for some  $t$  in  $X. \forall i$ . But  $\lim_{n \rightarrow \infty} d(A_i S_i x_n, S_i A_i x_n) \forall i$  is either non zero or does not exist.

Since  $A_i X \subset T_i X \forall i$ , corresponding to each  $x_n$  there exists  $y_n$  in  $X$  such that  $A_i x_n = T_i y_n \forall i$  and

$A_i x_n = T_i y_n \rightarrow t$ . By using (ii) and we have  $\lim_{n \rightarrow \infty} A_i y_n = t \forall i$ .

Thus we get sequences  $\{x_n\}$  and  $\{y_n\}$  in  $X$  such that  $A_i x_n \rightarrow t, S_i x_n \rightarrow t, T_i y_n \rightarrow t$  and  $A_i y_n \rightarrow t \forall i$ .

where  $T_i y_n = A_i x_n \forall i$ .

Now, suppose that  $S_i \forall i$ , the range of  $S_i \forall i$  is a complete subspace of X. Then, Since  $\lim_{n \rightarrow \infty} S_i x_n = t \forall i$ , there exists a point  $u$  in  $X$  such that  $t = S_i u \forall i$

Therefore,  $\lim_{n \rightarrow \infty} A_i x_n = \lim_{n \rightarrow \infty} B_i y_n = \lim_{n \rightarrow \infty} T_i y_n = \lim_{n \rightarrow \infty} S_i x_n = S_i u \forall i$

$d(A_i u, B_i y_n) < M_{ii}(x, y) = \max \{d(S_i u, T_i y_n), d(A_i u, S_i u), d(B_i y_n, T_i y_n), [d(S_i u, B_i y_n) + d(A_i u, T_i y_n)]/2\} \forall i$ .

$= \max \{d(A_i u, B_i y_n), 0\} = d(A_i u, B_i y_n) \forall i$ .

Therefore,  $d(A_i u, B_i y_n) < d(A_i u, B_i y_n) \forall i$ . Which is a contradiction.

Hence  $A_i u = S_i u \forall i$ .

Since  $A_i X \subset T_i X \forall i$ , there exists  $w$  in  $X$  such that  $A_i u = T_i w \forall i$ . If  $A_i u \neq B_i w$  for all  $i$ , using (ii)

We obtain  $d(A_i u, B_i w) < M_{ii}(u, w) = \max \{d(S_i u, T_i w), d(A_i u, S_i u), d(B_i w, T_i w), [d(S_i u, B_i w) + d(A_i u, T_i w)]/2\} \forall i$ .

$= \max \{d(B_i w, A_i u), [d(A_i u, B_i w) + 0]/2\} = d(A_i u, B_i w)$ .

$d(A_i u, B_i w) < d(A_i u, B_i w) \forall i$ . Which is a contradiction

Hence,  $S_i u = A_i u = T_i w = B_i w \forall i$ .

Next let us assume that  $T_i X \forall i$  is a complete subspace of X.

Then since  $\lim_{n \rightarrow \infty} T_i y_n = t \forall i$  there exists a point  $w$  in  $X$  such that  $t = T_i w \forall i$

If  $B_i w \neq T_i w$  using (ii) for sufficiently large values of  $n$ ,

We get  $d(A_i x_n, B_i w) \leq M_{ii}(x, y) = \max \{ d(S_i x_n, T_i w), d(A_i x_n, S_i x_n), d(B_i w, T_i w), [d(S_i x_n, B_i w) + d(A_i x_n, T_i w)]/2 \}$

On letting  $n \rightarrow \infty$ , we have  $d(T_i w, B_i w) < d(T_i w, B_i w)$  Which is a contradiction.  $\forall i$ .

Hence  $T_i w = B_i w \forall i$ .

Since  $B_i X \subset S_i X \forall i$ , there exists  $u$  in  $X$  such that  $T_i w = A_i w = S_i u \forall i$

using (ii) we get  $T_i w = B_i w = S_i u = A_i u \forall i$

Again using (ii) we get  $S_i u = A_i u = T_i w = B_i w \forall i$

Thus irrespective of whether  $S_i X \forall i$  is assumed complete or  $T_i X \forall i$  is assumed to be so.

we get  $u, w$  in  $X$  such that  $A_i u = S_i u = T_i w = B_i w \forall i$

Point wise R-weak commutativity of  $A_i$  and  $S_i \forall i$  implies that there exists  $R_i > 0$  such that  $d(A_i S_i u, S_i A_i u) \leq R_i d(A_i u, S_i u) = 0$

That is  $A_i S_i u = S_i A_i u \forall i$  and  $A_i A_i u = A_i S_i u = S_i A_i u = S_i S_i u \forall i$

Similarly, for every  $i$ , there exists  $R_i > 0$  such that  $d(B_i T_i w, T_i B_i w) \leq R_i d(B_i w, T_i w) = 0$ , that is

$B_i w T_i w = T_i w B_i w \forall i$  and  $B_i w B_i w = B_i w T_i w = T_i w B_i w = T_i w T_i w \forall i$

If  $A_i A_i u \neq A_i u \forall i$ , using (ii) we get  $d(A_i A_i u, A_i u) = d(A_i A_i u, B_i w) < M_{ii}(A_i u, w) = d(A_i A_i u, B_i w) \forall i$

Which is a contradiction. Hence  $A_i u = A_i A_i u = S_i A_i u \forall i$  and  $A_i u$  is a common fixed point of  $A_i$  and  $S_i \forall i$ .

Similarly, if  $B_i B_i w \neq B_i w \forall i$  using (ii) we have  $d(B_i w B_i w) = d(A_i u, B_i B_i w) < M_{ii}(u, B_i w) = d(A_i u, B_i B_i w) \forall i$  which is a contradiction.

Hence  $B_i w = B_i B_i w = T_i B_i w \forall i$  that is  $B_i w = A_i u$  is a common fixed point of  $T_i$  and  $B_i \forall i$

Uniqueness. Suppose  $u, v$  are fixed point of  $A_i, B_i, T_i$  and  $S_i \forall i$

Then  $A_i u = S_i u = B_i u = T_i u = u \forall i$  and

$A_i v = S_i v = B_i v = T_i v = v \forall i$

$d(u, v) = d(A_i u, B_i v) < \max \{ d(S_i u, T_i v), d(A_i u, S_i u), d(B_i v, T_i v), [d(S_i u, B_i v) + d(A_i u, T_i v)]/2 \}$

$= \max \{ d(u, v), 0, 0, [d(u, v) + d(u, v)]/2 \} = \max \{ d(u, v), d(u, v) \} = d(u, v)$

$= < < =$  when  $u \neq v$ .

Therefore  $u = v$ .

The proof is similar when  $B_i X$  is assumed complete for some  $i$ .

Since,  $A_i X \subset T_i X$  and  $B_i X \subset S_i X \forall i$ .

Therefore proof is complete.

**Theorem 3.2.** Let  $\{A_i\}, \{B_i\}, \{S_i\}, \{T_i\} \forall i=1,2,3,\dots$  be self-mappings of a metric space  $(X, d)$  such that  $A_i X \subset T_i X, B_i X \subset S_i X \forall i$  and (i) Pairs  $(A_i, S_i)$  and  $(B_i, T_i) \forall i$  are Point wise R-weakly commuting with atleast one non pair compatible, one non Compatible.

(ii)  $d(A_i x, B_i y) < M_{ii}(x, y) = \max \{ d(S_i x, T_i y), d(A_i x, S_i x), d(B_i y, T_i y), d(S_i x, B_i y), d(A_i x, T_i y) \} \forall i$  whenever  $M_{ii}(x, y) > 0$ .

If one of the mappings in the Compatible pair is continuous then all the  $A_i, B_i, S_i$  and  $T_i \forall i$  have a unique common fixed point.

**Proof.** Let  $B_i$  and  $T_i \forall i$  be a non compatible mappings and  $A_i$  and  $S_i \forall i$  be continuous compatible mappings. Then non compatible of  $B_i$  and  $T_i \forall i$  implies that there exists some sequence  $\{x_n\}$  in  $X$  such that  $\lim_{n \rightarrow \infty} B_i x_n = \lim_{n \rightarrow \infty} T_i x_n = t \forall i$  for some  $t$  in  $X$

While  $\lim_{n \rightarrow \infty} d(B_i T_i x_n, T_i B_i x_n) \forall i$  is either non zero or nonexistent. Since  $B_i X \subset S_i X \forall i$

Corresponding to each  $x_n$  there exists a  $y_n$  in  $X$  such that  $B_i x_n = S_i y_n \forall i$ .

Thus  $B_i x_n \rightarrow t, T_i x_n \rightarrow t$  and  $S_i y_n \rightarrow t \forall i$ .

We claim that  $A_i y_n \rightarrow t \forall i$ . If not, then there exists a subsequence  $\{A_i y_m\}$  of  $\{A_i y_n\} \forall i$

a number  $r > 0$  and a positive integer  $M$  such that for each  $m \geq M$ , we have  $d(A_i y_m, t) \geq r, d(A_i y_m, B_i x_m) \geq r \forall i$  and

$d(A_i y_m, B_i x_m) < \max \{ d(S_i y_m, T_i x_m), d(A_i y_m, S_i y_m), d(B_i x_m, T_i x_m), d(S_i y_m, B_i x_m), d(A_i y_m, T_i x_m) \} \forall i$

$= \max \{ d(A_i y_m, B_i x_m), d(A_i y_m, B_i x_m) \} = d(A_i y_m, B_i x_m) \forall i$ . which is a contradiction.

Hence  $\lim_{n \rightarrow \infty} A_i y_n = t, \lim_{n \rightarrow \infty} S_i y_n = t, \lim_{n \rightarrow \infty} B_i x_n = t$ , and  $\lim_{n \rightarrow \infty} T_i x_n = t \forall i$ ,

Where  $S_i y_n = B_i x_n \forall i$ . Since,  $A_i$  and  $S_i \forall i$  are continuous, we get  $\lim_{n \rightarrow \infty} S_i A_i y_n = S_i t \forall i$

and  $\lim_{n \rightarrow \infty} A_i S_i y_n = A_i t \forall i$  compatibility of  $A_i$  and  $S_i \forall i$  implies that  $\lim_{n \rightarrow \infty} d(A_i S_i y_n, S_i A_i y_n) = 0 \forall i$ . That is,  $d(A_i t, S_i t) = 0 \forall i$ .

Thus  $A_i t = S_i t, \forall i$  Since  $A_i X \subset T_i X \forall i$ , there exists some point  $w$  in  $X$  such that  $A_i t = T_i w \forall i$

Now, if  $T_i w \neq B_i w \forall i$ .

$$d(A_i t, B_i w) < \max \{d(S_i t, T_i w), d(A_i t, S_i t), d(B_i w, T_i w), d(S_i t, B_i w), d(A_i t, T_i w)\} \forall i$$

$$d(A_i t, B_i w) < \max \{d(B_i w, A_i t), d(A_i t, B_i w)\} = d(B_i w, A_i t)$$

Therefore,  $d(A_i t, B_i w) < d(A_i t, B_i w) \forall i$ . Which is a contradiction.

Hence  $B_i w = T_i w \forall i$  and  $S_i t = A_i t = T_i w = B_i w \forall i$

Point wise R-weak commutativity of  $B_i$  and  $T_i \forall i$  implies that there exists  $R > 0$  such that

$$d(B_i T_i w, T_i B_i w) \leq R d(B_i w, T_i w) = 0 \forall i.$$

That is,  $B_i T_i w = T_i B_i w \forall i$ . More over  $B_i B_i w = B_i T_i w = T_i B_i w = T_i T_i w \forall i$

Similarly, compatibility of  $A_i$  and  $S_i \forall i$  implies that  $A_i S_i t = S_i A_i t$  and

$$A_i A_i t = S_i A_i t = S_i S_i t \forall i. \text{ Now if } A_i t \neq A_i A_i t \forall i, \text{ using (ii) we get } d(A_i t, A_i A_i t) = d(A_i A_i t, B_i w)$$

$$< M_{ii}(A_i t, w) = d(A_i A_i t, B_i w) \forall i. \text{ Which is a contradiction.}$$

Hence,  $A_i t = A_i A_i t = S_i A_i t \forall i$  and  $A_i t \forall i$  is a common fixed point of  $A_i$  and  $S_i \forall i$

Similarly,  $B_i w = A_i t \forall i$  is a common fixed point of  $B_i$  and  $T_i \forall i$ .

Uniqueness. Suppose  $u, v$  are fixed points of  $A_i, B_i, S_i$  and  $T_i \forall i$ .

Then  $A_i u = S_i u = B_i u = T_i u = u \forall i$  and

$$A_i v = S_i v = B_i v = T_i v = v \forall i \quad d(u, v) = d(A_i u, B_i v) < \max \{d(S_i u, T_i v), d(A_i u, S_i u), d(B_i v, T_i v), d(S_i u, B_i v), d(A_i u, T_i v)\} \forall i$$

$$= \max \{d(u, v), d(u, u), d(v, v), d(u, v)\} = d(u, v)$$

$$d(u, v) < d(u, v)$$

$$= > < = \text{ when } u \neq v.$$

Therefore,  $u = v$ .

The proof is similar when  $A_i$  and  $S_i \forall i$  are assumed noncompatible and  $B_i$  and  $T_i \forall i$  are assumed continuous compatible mappings.

Hence the theorem.

Remark 3.3. It follows from the above proof that the assumption of the theorem that one of pairs, say  $(B_i, T_i) \forall i$  is non compatible can be weakened in the following way: There exists a sequence  $\{x_n\}$  such that

$$d(B_i x_n, T_i x_n) \rightarrow 0 \forall i$$

(Equivalently, for any  $\epsilon > 0$ ,  $B_i$  and  $T_i \forall i$  have an  $\epsilon$ -coincidence point  $x_\epsilon$ , that is  $d((B_i x_\epsilon, T_i x_\epsilon)) < \epsilon \forall i$ )

and the sequence  $\{B_i x_n\}$  is convergent [then, automatically  $\{T_i x_n\} \forall i$  converges].

Example 3.4. Let  $X = [2, 20]$  with the  $d$  be the usual metric on  $X$ .

Define  $A_i, B_i, S_i, T_i : X \rightarrow X, i = 1, 2, 3, \dots$  by

$$A_i x = 2 \text{ for each } x,$$

$$S_i x = x \text{ if } x < 8, S_i x = 8 \text{ if } x > 8 \forall i$$

$$B_i x = 2, \text{ if } x = 2 \text{ or } > 5, B_i x = 8 \text{ if } 2 < x < 4, B_i x = 3 + x \text{ if } 4 < x < 5,$$

$$T_i x = 2, T_i x = 12 + x \text{ if } 2 < x < 4, T_i x = 9 + x \text{ if } 4 < x < 5, T_i x = x - 3 \text{ if } x > 5:$$

Then  $A_i, B_i, S_i$  and  $T_i \forall i$  satisfy all the conditions of the above theorem and have a unique common fixed point  $x = 2$ . It may be noted in this example that  $A_i$  and  $S_i \forall i$  are continuous compatible mappings while  $B_i$  and  $T_i \forall i$  are non-compatible point wise R-weakly commuting mappings.  $B_i$  and  $T_i \forall i$  are point wise R-weakly commuting since they commute at their coincidence points. To see that  $B_i$  and  $T_i \forall i$  are noncompatible, let us consider a decreasing sequence  $\{x_n\}$  in  $X$  such that  $x_n \rightarrow 5$ . Then  $B_i x_n = 2, \forall i$

$$T_i x_n = x_n - 3 \rightarrow 2, T_i B_i x_n = T_i 2 = 2 \forall i$$

and  $B_i T_i x_n = B_i(x_n - 3) = 8. \forall i$  Hence  $B_i$  and  $T_i \forall i$  are noncompatible.  $A_i, B_i, S_i$  and  $T_i \forall i$  satisfy the contractive condition (1) but do not satisfy the contractive conditions (2) and (3). To show that (1) holds observe that  $d(A_i x, B_i y) = 0$  for  $y = 2$  or  $> 5, \forall i$  and  $d(A_i x, B_i y) < d(B_i y, T_i y) < M_{ii}(x, y)$  if  $2 < y < 5. \forall i$

To show that condition (2) is not satisfied, put  $x = 8$  and  $y_n = 5 - 1/n$ . Then

$$d(A_i 8, B_i y_n) = 1 + y_n \rightarrow 6 \text{ and } M_{ii}(8, y_n) = 6, \forall i \text{ and we see that } \phi(t) \text{ cannot be defined at}$$

$t = 6$ . Therefore, (2) does not hold.

Hence condition (3) is not satisfied either, because, as shown in [3], conditions (2) and (3) are equivalent. In fact, the function  $\delta(\epsilon)$  of condition (3) is also undefined at  $\epsilon = 6$ . To see this, let  $x = 8, y_n = 2 + 1/n$ , then

$$d(A_i 8, B_i y_n) = 6 \text{ and } M_{ii}(8, y_n) = 6 + 1/n, \text{ and hence } \delta(\epsilon) \text{ satisfying (3) cannot be defined at } \epsilon = 6.$$

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