# Slip and Pulsatile Mhd Blood Flow Through An Inclined Stenosed Artery With Body Acceleration And Heat Source Effects.

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# Abstract

We shall be studying theoretically the effects of body acceleration, heat source and slip on a pulsatory blood flow where the blood is assumed to be an unsteady, non-Newtonian blood flow flowing through an artery with stenosis present at the porous artery walls which is permeable with the results from the study discussed. The application of the magnetic field is in the region perpendicular to the inclined artery with a permeable walland stenosis at the wall with theinclination angle varying where the fluid flowing through the artery is anelasticviscous and electrically conducting fluid. The dimensional momentum equation was transformed to a dimensionless form and the Frobeniusseries solution wasgotten for the symmetric axial differential momentum equation with the applied boundary conditions. For clarity of the applicability of the study, results was shown graphically with behavior of the blood flow through the artery with stenosis shown for the velocity in the axial direction, blood acceleration, wall shear stress and volumetric flow rate.

**Keywords:** Magneto-hydrodynamic (MHD), Body acceleration, pulsatile pressure, Slip velocity, Permeability of the porous medium.

Date of Submission: 08-01-2022

Date of Acceptance: 22-01-2022

### Nomenclature

$P_0$	Pressure gradient in steady state
$P_l$	Pressure gradient in pulsatile state
w <sub>p</sub>	Amplitude of Pulse rate frequency
w <sub>b</sub>	Amplitude of the body frequency
fp	Heart pulse frequency
f <sub>b</sub>	Body acceleration frequency
$\tilde{G}_0$	Body acceleration
G(t)	Body acceleration dependent on time
Ø	Angleof inclined artery
Φ	Angle of phase difference
Z	Axial blood flow direction
t	Time
С	Blood concentration
θ	Blood energy
B <sub>0</sub>	Magnetic field
g	Acceleration due to gravity
D	Mass Diffusitycoefficient
Κ	Porosity coefficient
Re	Reynolds number
Cp	Specific heat capacity
Pe	Peclet number
S <sub>c</sub>	Schmidt number
r	Coordinates of the radial flow
Z	Coordinate of the Axial flow
μ	Coefficient Blood viscosity
ρ	Blood density
Kr	Chemical reaction term

- $\sigma$  Blood flow electrical conductivity
- Sc Schmidt number
- C<sub>p</sub> Specific heat capacity
- M Magnetic parameter
- θ Temperature
- G<sub>r</sub> Grashof energy number
- G<sub>c</sub> Grashof concentration number
- $\beta_T$  Volume expansion Coefficient due to temperature
- $\beta_C$  Volume expansion Coefficient due to concentration.
- $C_w$  Artery wall concentration
- T<sub>w</sub> Artery wall temperature
- *H* Heat source term
- $\delta$  Stenosis height
- l<sub>0</sub> Stenosis length,
- R(z) Radius of the stenotic vessel
- $R_0$  Radius of the normal artery
- s Stenosis shape term
- ξ Tapering term
- d Stenosis position.

# I. Introduction.

Thistheoretical study analysis the flow of blood through an inclined artery having stenosis at the artery walls with the effect of heat source and body acceleration whichhas immense significance and importance in the growth of tumor and cardiovascular disease. Blood flow can be both steady and unsteady where it doesn't depend on time and on the other hand depends on time. Certain factors can affect the viscosity of the blood where the shear stress could reduce its viscosity because of certain factors such as heat source and agitation of the blood due to body acceleration effect. The pulsatile blood flowpast an artery has caught the attention from researchers because of the relevant applicability in the biotechnological, biomedical and medical sciences. Blood circulation takes place when blood is pumped from the heart to different muscles of the body through the arteries which transports the blood the body muscles where the stenosis is present due to plaques of cholesterols could help to increase blood flow and arrest diseases resulting to hypotension for cardiac failure. Furthermore the application of heat source and induced slip at the wall can help treat ailments such as cancer and tumor growth.

Stenosis in the artery affects blood flowing from the heart through the arteryRabbi et al. [1] and Ellahi et al. [2].Pralhad et al. [3] studied the blood flow through the artery with stenosis with the wall shear stress and the resistance at the wall while Ellahi et al. [4] did a mathematical model explaining the blood flow through an artery with a composite stenosis. Magnetic field applied on bio fluids have effect on the dynamics of the fluid hence this fluids are bio magnetic fluids with rich application in medical sciences and biomedical engineering.Haik et al. [5] gave a clear distinction between bio magnetic fluid (BFD) and hydro magnetic fluid (MHD).Abdullah et al. [6] studied the effect of magneto-hydrodynamic on the flow of blood through a stenosis that is irregular with the results obtained from the study showing that, the rate of flow of blood reduced as a result of magnetic field applied to the arterial segment. Prakash et al. [7] did a study on the Magneto-hydrodynamic blood flow through an artery that is bifurcated with the effect of heat source where the blood flowing past the artery is considered to be unsteady and a non-Newtonian fluid. The results showed that the magnetic field and the heat source modify the pattern of the blood flow while the temperature of the blood is increased with heat source increasing the velocity.

Srivastava [8] did an analysis of the blood flow motion that is steady through an artery inclined with applied magnetic field with the conclusion that velocity of the blood flow decreases as a result of the increase in the magnetic field. The study showed that MHD fluids had electrically conducting properties due to the magnetic field applied to the fluid. Eldesoky [9] proposed a mathematical modelling of blood flow that is parallel with applied magnetic field in the transverse direction with effect of heat source. Results showed that increase in the heat source increases the temperature and axial velocity while increase in the decay reduces the temperature and axial velocity.Sudden change in the velocity could disturb the flow of blood through the artery hence having an effect on the blood flow. The prolonged sudden velocity change with the inclined body artery caused by body movement during aircraft flight, car driving, etc., could have a dangerous effect on the human body. Saddiqui, et al. [10] studied the effect of slip and body acceleration on the pulsatile flow of blood on a casson fluid flowing through a stenotic artery. Sinha et al. [11] did a study on the slip and periodic body accelerationeffect on pulsatile flow of bloodpassing through asegmented stenosedartery. Sinha et al. [12] did a

study on the effect of the transfer of heat on unsteady Magneto-hydrodynamic blood flow in a vessel that is permeable with non-uniform heat source present. The stretching velocity that is time-dependent and surface temperature of the vessel causes unsteady coupled flow and temperature fields with the heat source/sink effect on the blood flow which non-uniform was considered. The study showed its clinical application in treating cardiovascular disorders with accelerated circulation. Tripathi and Sharma [13] did a study on heat and mass transfer effects of a blood flow two phases which is pulsatile past a stenosed artery that is narrow with chemical reaction and radiation. Karthikeyan and Jeevitha [14] did a study analysis on the effect of heat and mass transfer on a model in two phases for unsteady blood flow that is pulsatile past an artery with stenosis having a wall that is permeable with radiation and chemical reaction effects. Abubakar and Adeoye [15] did a study analyzing the effect of heat radiation and magnetic field on blood flowing in a tapered and inclined porous artery with stenosis. Amos and Ogulu [16] studied the magnetic field effect on Pulsatile Blood Flow through an axis-symmetric channel that is constricted.Bunonyo and Amos [17] studied the effect of lipid concentration on the blood that flows through an artery channel inclined with magnetic field present.

This study has theoretically analyzed, showingthe effects ofslip, heat source, body acceleration, inclined artery angle and pulsatile pressure on the non-Newtonian unsteady blood flow through astenotic artery. The artery walls is porous and permeable with the analysis done by solving the problem of the governing equation using the Frobenuis power series method to obtain the velocity of the blood flow, blood acceleration, wall shear stress and volumetric flow rate solutions with a graph illustrating thebehavior of the effect of slip, heat source, body acceleration, magnetic field, pulsatile pressure gradient and inclined artery on the blood flow velocity, blood acceleration, shear stress and volumetric flow rate.

# II. Formulation of the problem

The motion of the flow of blood is axisymmetric with the coordinate's ( $r', \theta', z'$ ) flowing horizontally in the axisz'. The one dimensional blood flow is transported past a rigid and cylindrical stenotic artery whose walls are porous with permeability where the fluid considered is an incompressible, non-Newtonian, viscous, electrically conducting blood fluid under the influence of a magnetic field applied normal to the tangential artery. The height and the position of the stenosis is dependent on the height of the constricted artery wall.



Figure 1.1 Flow geometry of the stenotic artery

The geometry of the one dimensional blood flow through the segmented stenotic artery, symmetrical in shape was proposed by Eldesoky[18] and Kumar et al. [19] as,

$$R(z') = \begin{cases} d'(z) - \frac{\delta'}{2} \left[ 1 + \cos \frac{2\pi}{l_0} \left\{ z' - d' - \frac{l'_0}{2} \right\} \right] \\ d'(z) \end{cases}, d' \le z' \le d' + l'_0$$
(1)

The greateststenosis height (R)happens at the center, Nadeem et al. [20].

$$z = d + \frac{L_0}{s(\frac{1}{s-1})}$$
 For  $s \ge 2$  and  $l_1 = \frac{d}{R'_0}$ 

# III. Governing equation

The blood temperature and blood flow velocity which is steady and unsteady flowing past an inclined artery with the applied magnetic field in the radial direction perpendicular to the axial direction is considered

$$\rho \frac{\partial u}{\partial t'} = -\frac{\partial p}{\partial z'} + \rho G(t) + \mu \frac{\partial}{\partial r'} \left( r' \frac{\partial u}{\partial r'} \right) - \sigma_c B_0^2 u' + g \sin \phi - \frac{\mu}{k_p'} u'$$

$$Pe \frac{\partial \theta}{\partial t} = \frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} + N^2 \theta$$
(3)

The non-dimensional form of pressure gradient is expressed as

$$-\frac{\partial p'}{\partial z'} = P'_{0} + P'_{1} \cos(w_{p} t'); \ t \ge 0$$
(4)

$$\begin{array}{ll} \mbox{Where } w_{\rm p} = 2\pi f_{\rm p} \mbox{ and } w_{\rm b} = 2\pi f_{\rm b} \\ G(t) = G_0 \cos(w_{\rm b}t' + \phi); \ t \geq 0 \\ \mbox{The dimensionless flow geometry with stenosis, Eldesoky[18] and Kumar et al. [19].} \\ R(z) = \begin{cases} (1 + \xi z) - \frac{\delta}{2} \left[ 1 + \cos \frac{2\pi}{l_0} \left\{ z - l_1 - \frac{l_0}{2} \right\} \right] \\ (1 + \xi z) \end{cases}, l_1 \leq z \leq l_1 + l_0 \\ (1 + \xi z) \end{cases} \tag{6}$$
 The non-dimensional body acceleration and Pressure gradient  $G(t) = G_0 \cos(bt + \phi); t \geq 0 \\ - \frac{\partial p}{\partial z} = P_0 + P_l \cos(w_p t); t \geq 0 \end{cases}$  (7a) (7b) The momentum equation in dimensionless form is written as for first consideration:

$$\operatorname{Re} \frac{\partial u}{\partial t} = P_0 + P_L \cos t + G_0 \cos(bt + \phi) + \left(\frac{\partial^2 u}{\partial r^2} + \frac{1}{r}\frac{\partial u}{\partial r}\right) - \left(M^2 + \frac{1}{K}\right)u + \frac{\sin \phi}{Fr}$$

$$\operatorname{Pe} \frac{\partial \theta}{\partial t} = \frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r}\frac{\partial \theta}{\partial r} + N^2\theta$$
(8)

$$\operatorname{Pe}\frac{\partial \theta}{\partial t} = \frac{\partial}{\partial r^2} + \frac{1}{r}\frac{\partial \theta}{\partial r} + N^2\theta \tag{9}$$

The dimensional initial and boundary slip conditions are (∂u'

$$\begin{cases} \frac{\partial \mathbf{u}'}{\partial \mathbf{r}'} = -\mathbf{h}'\mathbf{u}', \mathbf{T}' = \mathbf{T}'_{a} \text{ at } \mathbf{r}' = \mathbf{R}'(\mathbf{z}) \\ \frac{\partial \mathbf{u}'}{\partial \mathbf{u}'} = \mathbf{0}, \frac{\partial \mathbf{\theta}'}{\partial \mathbf{u}'} = \mathbf{0} \qquad \text{ at } \mathbf{r}' = \mathbf{0} \end{cases}$$
(10a)

The dimensionless initial and boundary slip conditions are

$$\begin{cases} \frac{\partial u}{\partial r} = -hu, \theta = \theta_a & \text{at } r = R(z) \\ \frac{\partial u}{\partial r} = 0, \frac{\partial \theta}{\partial r} = 0 & \text{at } r = 0 \end{cases}$$
(10b)

 $\eta$  depends on the property of the porous material, K is the permeability parameter.

$$a = \frac{R(z)}{R_0 + \xi z}; \xi = \tan \emptyset, h = -\frac{\eta}{R_0 \sqrt{K}}$$

Non dimensional parameters in the governing equations and boundary conditions are transformed to dimensionless form.

$$\begin{aligned} u &= \frac{u'}{u_0}; \delta = \frac{\delta'}{R'_0}; \ d(z') = R_0 + \xi z'; \ r &= \frac{r'}{R'_0}; z = \frac{z'}{R'_0}; b = \frac{w_b}{w_p}; \ t = w_p t'; R(z) = \frac{R'(z)}{R'_0}; P = \frac{R'_0\rho'}{u_0\mu}; Re = \frac{\rho\omega R'_0\rho'}{u_0\mu}; \theta = \frac{r' - T_0}{r'_w - T_0}; \theta_a &= \frac{T_a' - T_0}{T'_w - T_0}; C = \frac{C' - C_{\infty}}{C'_w - C_{\infty}}; C_a &= \frac{C_a' - C_{\infty}}{C'_w - C_{\infty}} \delta = \frac{\delta'}{R'_0}; \ N^2 &= \frac{R'_0\rho'}{\rho c_p k'_p}; \ M^2 &= \frac{\sigma R'_0\rho'}{\mu}; \ P_e &= \frac{\rho R'_0\rho'}{k'_p}; \ S_c &= \frac{\vartheta}{D'}; Kr = \frac{E' R'_0\rho'}{\vartheta c_p}; \ G_r &= \frac{g\rho R'_0\rho'}{u_0\mu}; \ G_c &= \frac{g\rho R'_0\rho'}{u_0\mu}; \ P_l &= \frac{P'_1R'_0\rho'}{u_0\mu}; \ P_0 &= \frac{P'_0R'_0\rho'}{u_0\mu}; \ G_0 &= \frac{\rho G'_0R'_0\rho'}{u_0\mu}; \ f_r &= \frac{u_0\mu}{gR'_0\rho'}; \ D &= \frac{D'}{D_0}; \ K &= \frac{k'_p\rho'}{R'_0\rho'}; \end{aligned}$$

#### IV. **Method of Solution**

The differential equation analytically solved using the Frobenius method. The solutions of the governing nonlinear partial differential equation for the steady and pulsatile blood flow velocity and blood temperature is expressed as a function of time

$$\mathbf{u}(\mathbf{r},\mathbf{t}) = \mathbf{u}_0(\mathbf{r}) + \mathbf{u}_p(\mathbf{r})\varepsilon \mathbf{e}^{\mathrm{i}\mathbf{w}\mathbf{t}}$$
(12)

$$\theta(\mathbf{r}, \mathbf{t}) = \theta_0(\mathbf{r}) + \theta_p(\mathbf{r}) \epsilon e^{iwt}$$

#### V. Solution to the Governing equation

The temperature for the steady and pulsatile state is expressed below as

$$\frac{\partial^2 \theta_0}{\partial r^2} + \frac{1}{r} \frac{\partial \theta_0}{\partial r} + N^2 \theta_0 = 0$$
(14)

$$\frac{\partial^2 \theta_p}{\partial r^2} + \frac{1}{r} \frac{\partial \theta_p}{\partial r} + \alpha_1 \theta_p = 0$$
(15)

Where  $\alpha_1 = N^2 - i\omega Pe$ 

The blood flow velocity for the steady and pulsatile state is expressed below as  $\partial^2 u_0$ ,  $1 \partial u_0$ ~ ~ ~

$$\frac{\partial^2 u_0}{\partial r^2} + \frac{1}{r} \frac{\partial u_0}{\partial r} - \beta_1 u_0 = -G - G_r \theta_0$$
(16)
$$\frac{\partial^2 u_p}{\partial r^2} + \frac{1}{r} \frac{\partial u_p}{\partial r} - \beta_2 u_p = -F - G_r \theta_n$$
(17)

$$\beta_1 = M^2 + \frac{1}{\kappa}; \ G = P_0 + \frac{\sin \phi}{F_r}; \ \beta_2 = M^2 + \frac{1}{\kappa} + \text{ReiwandF} = P_1 \cos t + G_0 \cos(bt + \phi)$$

(13)

The power series solution for the steady state and the pulsatile state for both the temperature and blood flow velocity using the Funch's theorem, called the Frobenius series expressed as

$$\begin{aligned} \theta_{0}(r) &= \sum_{n=0}^{\infty} a_{n} r^{n+k} \text{Where} a_{n}, k \in \mathcal{C}_{1} \end{aligned} \tag{18} \\ \theta_{p}(r) &= \sum_{n=0}^{\infty} b_{m} r^{m+k} \text{Where} b_{m}, k \in \mathcal{C}_{2} \end{aligned} \tag{19} \\ u_{0} &= \sum_{n=0}^{\infty} c_{n} r^{n+k} \text{Where} c_{n}, k \in \mathcal{C}_{3} \end{aligned} \tag{20} \\ u_{p} &= \sum_{m=0}^{\infty} d_{m} r^{m+k} \text{Where} d_{m}, k \in \mathcal{C}_{4} \end{aligned} \tag{21}$$

The temperature in the steady state is expressed as

$$\theta_{0} = C_{1} \left[ 1 - \frac{N^{2}r^{2}}{2^{2}} + \frac{N^{4}r^{4}}{2^{2}4^{2}} - \frac{N^{6}r^{6}}{2^{2}4^{2}6^{2}} + \frac{N^{8}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right] + D_{1} \left[ \frac{\ln r \left( 1 - \frac{N^{2}r^{2}}{2^{2}} + \frac{N^{4}r^{4}}{2^{2}4^{2}} - \frac{N^{6}r^{6}}{2^{2}4^{2}6^{2}} + \frac{N^{8}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right) + \left( \frac{N^{2}r^{2}}{2^{2}} - \frac{3N^{4}r^{4}}{2^{3}4^{2}} + \frac{N^{6}r^{6}}{4^{3}6^{3}} + \frac{N^{8}r^{8}}{2^{5}6^{3}8^{3}} - \cdots \right) \right) \right]$$
(22)

Apply the boundary condition in equation (10) to equation (22) with  $D_1 = 0$ , then

$$\theta_{0} = C_{1} \left[ 1 - \frac{N^{2}r^{2}}{2^{2}} + \frac{N^{4}r^{4}}{2^{2}4^{2}} - \frac{N^{6}r^{6}}{2^{2}4^{2}6^{2}} + \frac{N^{8}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right]$$

$$Where C_{1} = \frac{\theta_{R}}{\left[ 1 - \frac{N^{2}R^{2}}{2^{2}} + \frac{N^{4}R^{4}}{2^{2}4^{2}} - \frac{N^{6}R^{6}}{2^{2}4^{2}6^{2}} + \frac{N^{8}R^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right]$$

$$(23)$$

The temperature in the pulsatile state is expressed as

$$\theta_{p} = C_{2} \left[ 1 - \frac{\alpha_{1}r^{2}}{2^{2}} + \frac{\alpha_{1}^{2}r^{4}}{2^{2}4^{2}} - \frac{\alpha_{1}^{3}r^{6}}{2^{2}4^{2}6^{2}} + \frac{\alpha_{1}^{4}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right] + D_{2} \begin{bmatrix} \ln r \left( 1 - \frac{\alpha_{1}r^{2}}{2^{2}} + \frac{\alpha_{1}^{2}r^{4}}{2^{2}4^{2}} - \frac{\alpha_{1}^{3}r^{6}}{2^{2}4^{2}6^{2}} + \frac{\alpha_{1}^{4}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right) + \\ \left( \frac{\alpha_{1}r^{2}}{2^{2}} - \frac{3\alpha_{1}^{2}r^{4}}{2^{3}4^{2}} + \frac{\alpha_{1}^{3}r^{6}}{4^{3}6^{3}} + \frac{\alpha_{1}^{4}r^{8}}{2^{5}6^{3}8^{3}} - \cdots \right)$$

$$(24)$$

Apply the boundary condition in equation (10) to equation (24) with  $D_2 = 0$ , then

$$\theta_{P} = C_{2} \left[ 1 - \frac{\alpha_{1}r^{2}}{2^{2}} + \frac{\alpha_{1}^{2}r^{4}}{2^{2}4^{2}} - \frac{\alpha_{1}^{3}r^{6}}{2^{2}4^{2}6^{2}} + \frac{\alpha_{1}^{4}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right]$$

$$Where C_{2} = \frac{\theta_{R}}{\left[ 1 - \frac{\alpha_{1}R^{2}}{2^{2}} + \frac{\alpha_{1}^{2}R^{4}}{2^{2}4^{2}} - \frac{\alpha_{1}^{3}R^{6}}{2^{2}4^{2}6^{2}} + \frac{\alpha_{1}^{4}R^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right]$$

$$(25)$$

The solution for the temperature in equation (13) is gotten by combining both equation (23) and (25) which is expressed as

$$\theta(\mathbf{r},\mathbf{t}) = C_1 \left[ 1 - \frac{N^2 r^2}{2^2} + \frac{N^4 r^4}{2^2 4^2} - \frac{N^6 r^6}{2^2 4^2 6^2} + \frac{N^8 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + \left( C_2 \left[ 1 - \frac{\alpha_1 r^2}{2^2} + \frac{\alpha_1^2 r^4}{2^2 4^2} - \frac{\alpha_1^3 r^6}{2^2 4^2 6^2} + \frac{\alpha_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + \left( C_2 \left[ 1 - \frac{\alpha_1 r^2}{2^2} + \frac{\alpha_1^2 r^4}{2^2 4^2} - \frac{\alpha_1^3 r^6}{2^2 4^2 6^2} + \frac{\alpha_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] \right) \right)$$
where the set of the s

The complementary solution for the blood flow velocity in the steady state in equation (16) is expressed as

$$u_{0c} = C_3 \left[ 1 + \frac{\beta_1 r^2}{2^2} + \frac{\beta_1^2 r^4}{2^2 4^2} + \frac{\beta_1^3 r^6}{2^2 4^2 6^2} + \frac{\beta_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + D_3 \begin{bmatrix} \ln r \left( 1 + \frac{\beta_1 r^2}{2^2} + \frac{\beta_1^2 r^4}{2^2 4^2} + \frac{\beta_1^3 r^6}{2^2 4^2 6^2} + \frac{\beta_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right) + \\ \left( -\frac{\beta_1 r^2}{2^2} - \frac{3\beta_1^2 r^4}{2^3 4^2} - \frac{\beta_1^3 r^6}{4^3 6^3} + \frac{\beta_1^4 r^8}{2^5 6^3 8^3} - \cdots \right) \end{bmatrix}$$
(27)

Apply the boundary condition in equation (10) to equation (27) with  $D_3 = 0$ , then

$$u_{0c} = C_3 \left[ 1 + \frac{\beta_1 r^2}{2^2} + \frac{\beta_1^2 r^4}{2^2 4^2} + \frac{\beta_1^3 r^6}{2^2 4^2 6^2} + \frac{\beta_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right]$$
(28)

The particular solution for the steady state blood flow velocity in equation (16) is expressed as

$$u_{0p} = M_0 + M_1 r^2 + M_2 r^4 + M_3 r^6 + M_4 r^8$$
<sup>(29)</sup>

The solution for the blood flow velocity in equation (16) is the combination of equation (28) and (29).

$$u_0 = C_3 \left[ 1 + \frac{\beta_1 r^2}{2^2} + \frac{\beta_1^2 r^4}{2^2 4^2} + \frac{\beta_1^3 r^6}{2^2 4^2 6^2} + \frac{\beta_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + M_0 + M_1 r^2 + M_2 r^4 + M_3 r^6 + M_4 r^8$$
(30)

Where  $C_3 = -$ 

$$\frac{\left[h(M_0 + M_1R^2 + M_2R^4 + M_3R^6 + M_4R^8) + 2M_1R + 4M_2R^3 + 6M_3R^5 + 8M_4R^7\right]}{\left[\frac{\beta_1R^2}{2} + \frac{\beta_1^2R^3}{2^24} + \frac{\beta_1^3R^5}{2^24^26} + \frac{\beta_1^4R^7}{2^24^26^28} + \cdots\right] + h\left[1 + \frac{\beta_1R^2}{2^2} + \frac{\beta_1^2R^4}{2^24^2} + \frac{\beta_1^3R^6}{2^24^26^2} + \frac{\beta_1^4R^8}{2^24^26^28^2} + \cdots\right]$$

The complementary solution for the blood flow velocity in the pulsatile state in equation (17) is expressed as

$$\begin{split} u_{pc} &= C_4 \left[ 1 + \frac{\beta_2 r^2}{2^2} + \frac{\beta_2^2 r^4}{2^2 4^2} + \frac{\beta_2^3 r^6}{2^2 4^2 6^2} + \frac{\beta_2^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + D_4 \left[ \ln r \left( 1 + \frac{\beta_2 r^2}{2^2} + \frac{\beta_2^2 r^4}{2^2 4^2} + \frac{\beta_2^3 r^6}{2^2 4^2 6^2} + \frac{\beta_2^4 r^8}{2^2 4^2 6^2 8^2} + \right) + \frac{-\beta_2 r^2 2 2 - 3\beta_2 2 r 42342 - \beta_2 3 r 64363 + \beta_2 4 r 8256383 - \ldots}{(31)} \end{split}$$

Apply the boundary condition in equation (10) to equation (31) with  $D_4 = 0$ , then

$$u_{pc} = C_4 \left[ 1 + \frac{\beta_2 r^2}{2^2} + \frac{\beta_2^2 r^4}{2^2 4^2} + \frac{\beta_2^3 r^6}{2^2 4^2 6^2} + \frac{\beta_2^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right]$$
(32)

The particular solution for the pulsatile state blood flow velocity in equation (16) is expressed as

$$u_{pp} = L_0 + L_1 r^2 + L_2 r^4 + L_3 r^6 + L_4 r^8$$
(33)

The solution for the blood flow velocity in equation (17) is the combination of equation (32) and (33).

$$u_{P} = C_{4} \left[ 1 + \frac{\beta_{2}r^{2}}{2^{2}} + \frac{\beta_{2}^{2}r^{4}}{2^{2}4^{2}} + \frac{\beta_{2}^{3}r^{6}}{2^{2}4^{2}6^{2}} + \frac{\beta_{2}^{4}r^{8}}{2^{2}4^{2}6^{2}8^{2}} + \cdots \right] + L_{0} + L_{1}r^{2} + L_{2}r^{4} + L_{3}r^{6} + L_{4}r^{8}$$
(34)

Where  $C_4 = -$ 

$$\frac{\left[h(L_0+L_1R^2+L_2R^4+L_3R^6+L_4R^8)+2L_1R+4L_2R^3+6L_3R^5+8L_4R^7\right]}{\left[\frac{\beta_2R^2}{2}+\frac{\beta_2^2R^3}{2^24}+\frac{\beta_2^3R^5}{2^24^26}+\frac{\beta_2^4R^7}{2^24^26^28}+\cdots\right]+h\left[1+\frac{\beta_2R^2}{2^2}+\frac{\beta_2^2R^4}{2^24^2}+\frac{\beta_2^3R^6}{2^24^26^2}+\frac{\beta_2^4R^8}{2^24^26^28}+\cdots\right]}$$

The solution to the blood flow velocity in equation in equation (9) by substituting equation (30) and (34) into equation (12) is expressed as

$$u(r,t) = C_3 \left[ 1 + \frac{\beta_1 r^2}{2^2} + \frac{\beta_1^2 r^4}{2^2 4^2} + \frac{\beta_1^3 r^6}{2^2 4^2 6^2} + \frac{\beta_1^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + M_0 + M_1 r^2 + M_2 r^4 + M_3 r^6 + M_4 r^8 + \left( C_4 \left[ 1 + \frac{\beta_2 r^2}{2^2} + \frac{\beta_2^2 r^4}{2^2 4^2} + \frac{\beta_2^3 r^6}{2^2 4^2 6^2} + \frac{\beta_2^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] + L_0 + L_1 r^2 + L_2 r^4 + L_3 r^6 + L_4 r^8 \right) \varepsilon e^{iwt}$$
(35)

The Solution for the Fluid Acceleration equation

$$F(\mathbf{r}, \mathbf{t}) = \frac{du}{dt} = iw\varepsilon e^{iwt} \begin{pmatrix} C_4 \left[ 1 + \frac{\beta_2 r^2}{2^2} + \frac{\beta_2^2 r^4}{2^2 4^2} + \frac{\beta_2^3 r^6}{2^2 4^2 6^2} + \frac{\beta_2^4 r^8}{2^2 4^2 6^2 8^2} + \cdots \right] \\ + \frac{4L_1}{\beta_2} + \frac{GrC_2}{\beta_2} + L_1 r^2 + L_2 r^4 + L_3 r^6 + L_4 r^8 \end{pmatrix} + \varepsilon e^{iwt} \frac{P_l}{\beta_2} (iw\cos t - \sin t) + \varepsilon e^{iwt} \frac{G_0}{\beta_2} (iw\cos (bt + \varphi) - b\sin(bt + \varphi))$$
(36)

The Solution for the Wall Shear Stress equation

$$\frac{dr}{dr} = C_3 \left[ \frac{\beta_1 r}{2} + \frac{\beta_1^2 r^3}{2^2 4} + \frac{\beta_1^3 r^5}{2^2 4^2 6} + \frac{\beta_1^4 r^7}{2^2 4^2 6^2 8} + \cdots \right] + 2M_1 r + 4M_2 r^3 + 6M_3 r^5 + 8M_4 r^7 + \left( C_4 \left[ \frac{\beta_2 r}{2^2} + \frac{\beta_2^2 r^3}{2^2 4} + \frac{\beta_2^4 r^7}{2^2 4^2 6^2 8} + \cdots \right] + 2L1 r + 4L2 r^3 + 6L3 r^5 + 8L4 r^7 \varepsiloneiwt \right) + (37)$$

The Solution for the Volumetric Flow Rate equation

du

$$Q(\mathbf{r},\mathbf{t}) = 2\pi \int_{0}^{a} \mathbf{r} u(\mathbf{r},\mathbf{t}) d\mathbf{r} = \\ C_{3} \left[ \frac{a^{2}}{2} + \frac{\beta_{1}a^{4}}{2^{2}4} + \frac{\beta_{1}^{2}a^{6}}{2^{2}4^{2}6} + \frac{\beta_{1}^{3}a^{8}}{2^{2}4^{2}6^{2}8} + \frac{\beta_{1}^{4}a^{10}}{2^{2}4^{2}6^{2}8^{2}10} + \cdots \right] + \\ 2\pi \left\{ \frac{M_{0}a^{2}}{2} + \frac{M_{1}a^{4}}{4} + \frac{M_{2}a^{6}}{6} + \frac{M_{3}a^{8}}{8} + \frac{M_{4}a^{10}}{10} + \left( C_{4} \left[ \frac{a^{2}}{2} + \frac{\beta_{2}a^{4}}{2^{2}4} + \frac{\beta_{2}^{2}a^{6}}{2^{2}4^{2}6} + \frac{\beta_{2}^{3}a^{8}}{2^{2}4^{2}6^{2}8} + \frac{\beta_{2}^{4}a^{10}}{2^{2}4^{2}6^{2}8^{2}10} + \cdots \right] \right\} \varepsilon e^{iwt} \right\}$$

$$(38)$$

# VI. Graphical Results and Discussion.

In Figure 2.0, it was observed that the higher the heat source Hfrom  $0.5 \le H \le 2$ , resulted to an increase in the blood flow velocity at the artery center but approaches zero at the wall of the stenotic artery. This is because the increased heat reduces the blood viscosity hence causing an increase in blood flow. The increase in the blood flow at the wall of the artery results to an increase in both the blood acceleration and the volumetric flow rate in figure 3.0 and figure 5.0 but a decrease in the shear stress at the artery wall in figure 4.0.

In figure 6.0, it was observed that the higher the artery inclination  $\phi$  from  $15^0 \le \phi \le 60^0$ , resulted to the increase in the blood flow velocity at the center of the artery but tends to zero at the artery wall with stenosis. A fluctuating behavior was observed for the blood acceleration in figure 7.0, while the blood flow velocity increase caused an increase in the wall shear stress and volumetric flow rate in figure 8.0 and figure 9.0.

Figure 10.0, showed that an increased body acceleration Go caused an increase in blood flow due because the heart work rate increase which causes more blood to be pumped from the heart to the muscles. This increase results to an increase in the blood acceleration, shear stress at the walls of the artery with stenosis and volumetric flow rate in figure 11.0 to Figure 13.0.

In figure 14.0, it was observed that the increased Wormersely number caused the velocity of the blood flow to decrease. This decrease causes a decrease in the acceleration of blood, wall shear stress at the stenotic wall and volumetric flow rate from figure 15.0 to Figure 17.0.

In figure 14.0, it was seen that an as the body acceleration frequency b increased, the velocity of the blood flow decreased. This decrease results to an increase in the blood acceleration in figure 15.0 but a decrease in the shear stress at the artery walls and volumetric flow rate from figure 16.0 to Figure 17.0.

Figure 18.0, showed that increased permeability of porous wall k caused an increase the blood flow velocity because of the reduced viscous force at the artery walls. The increase causes an increase in acceleration of blood, shear stress at the wall of the artery and the volumetric flow rate from figure 19.0 to Figure 21.0. This conforms to study done by Tripathi and Sharma [21] andShina et al. [12].

Figure 22.0, showed that increased magnetic field M caused a decrease in the velocity of the blood flow caused by increased Lorentz force resist the flow of blood. This will decrease the acceleration of the blood, wall shear stress of the stenotic artery and the volumetric flow rate from figure 23.0 to Figure 25.0. This conforms to study done by Tripathi and Sharma [20], Wahab and Salemi [22] and Shina et al. [12].

An increase in heart work rate caused by the body acceleration increase, results to an increase in the pulsatile pressure Pl which increases the velocity of the blood flow in figure 26.0. The increase caused an increase in the acceleration of the blood, wall shear stress of the stenotic artery and the volumetric flow rate from figure 27.0 to figure 29.0.

An increased slip value h at the stenotic artery wall caused a decrease in the velocity and acceleration of the blood flow from figure 30.0 to figure 31.0. This was because the slip induced at the wall also opposes the blood flow hence reduces the blood flow and blood acceleration. This conforms to study done by Shina et al. [12]. The shear stress at the wall of the artery with stenosis becomes less in figure 32.0. The volumetric flow rate also reduced at the artery walls in figure 33.0. This conforms to study done by Tripathi and Sharma [21].

Over a prolonged time t in figure 34.0, the velocity of the blood flow decreased but the acceleration of the blood increased in figure 35.0 in figure 36.0 and figure 37.0, the shear stress and the volumetric flow rate decreases at the artery wall with stenosis.

An increased radius of stenosis R at the stenotic artery wall leads to reduction in stenosis height which caused an increase in the velocity and acceleration of the blood flow from figure 38.0 to figure 39.0. This was because the artery becomes open due to reduction in stenosis at the wall, hence aiding blood flow and blood acceleration. This conforms to study done by Tripathi and Sharma [21]. The shear stress at the wall of the artery with stenosis reduces in figure 40.0 while the volumetric flow rate increases at the artery walls in figure 41.0.

Finally the increase in the magnetic field and heat source increased the blood temperature in figure 42.0 and figure 43.0







Figure 5.0 Graph for the Volumetric Flow rate with increasing values of Heat SourceH = 0.5, 1, 1.5, 2, whenGr = 2, Pe = 1, Po = 2, Pl = 4, Go = 3, Fr = 0.05, b = 2,  $\phi$  = 30<sup>0</sup>,  $\beta$  = 30<sup>0</sup>, k = 0.1,  $\alpha$  = 1, h = 1, R = 0.55, M = 1.5,  $\xi$  = 0.1,  $\omega$  = 1, t = 1.

Velocity



4, Go = 3, Fr = 0.05, b = 2, k = 0.1,  $\alpha$  = 1, h = 1, R = 0.55, M = 1.5,  $\xi$  = 0.1,  $\omega$  = 1, t = 1.













 $0.1, \omega = 1, t = 1.$ 







Figure 18.0 Blood flow velocity distribution for increase in the Permeability of the porous wallk when Po = 2, Pl = 4, Go = 3, Fr = 0.05, b = 2,  $\phi$  = 45<sup>0</sup>,  $\beta$  = 30<sup>0</sup>,  $\alpha$  = 1, h = 1, R = 0.55, M = 1.5,  $\xi$  = 0.1,  $\omega$  = 1, t = 1.



Figure 19.0 Blood acceleration profile for increase in the Permeability of the porous wallk when Po = 2, Pl = 4, Go = 3, Fr = 0.05, b = 2,  $\beta$  = 30<sup>0</sup>,  $\alpha$  = 1, h = 1, R = 0.55, M = 1.5,  $\xi$  = 0.1,  $\omega$  = 1, t = 1.



1, t = 1.



1, t = 1.







Figure 27.0 Blood acceleration profile for increase in the Pulsatile pressure Pl when Po = 2, Go = 3, Fr = 0.05, b = 2,  $\phi$  = 45<sup>0</sup>,  $\beta$  = 30<sup>0</sup>, k = 0.1,  $\alpha$  = 1, h = 1, R = 0.55, M = 1.5,  $\xi$  = 0.1,  $\omega$  = 1, t = 1.



Figure 28.0 Wall shear stress profile for increase in the Pulsatile pressure Pl when Po = 2, Go = 3, Fr = 0.05, b = 2,  $\varphi = 45^{\circ}$ ,  $\beta = 30^{\circ}$ , k = 0.1,  $\alpha = 1$ , h = 1, R = 0.55, M = 1.5, a = 1,  $\xi = 0.1$ ,  $\omega = 1$ , t = 1.



Figure 29.0 Volumetric flow rate profile for increase in the Pulsatile pressure Pl when Po = 2, Go = 3, Fr = 0.05, b = 2,  $\varphi = 45^{0}$ ,  $\beta = 30^{0}$ , k = 0.1,  $\alpha = 1$ , h = 1, R = 0.55, M = 1.5, a = 1,  $\xi = 0.1$ ,  $\omega = 1$ , t = 1.



Figure 30.0 Blood flow velocity distribution for increase in the Slip Parameterh when Po = 2, Pl = 4, Go = 3, Fr = 0.05, b = 2,  $\phi = 45^{0}$ ,  $\beta = 30^{0}$ , k = 0.1,  $\alpha = 1$ , R = 0.55, M = 1.5,  $\xi = 0.1$ ,  $\omega = 1$ , t = 1.







Figure 32.0 Wall shear stress profile for increase in the Slip Parameterh when Po = 2, Pl = 4, Go = 3, Fr = 0.05, b = 2,  $\phi = 45^{\circ}$ ,  $\beta = 30^{\circ}$ , k = 0.1,  $\alpha = 1$ , R = 0.55, M = 1.5, a = 1,  $\xi = 0.1$ ,  $\omega = 1$ , t = 1.





























Figure 42.0 Graph for the Temperature with increasing values of Magnetic field when  $\alpha = 1$ , R =  $0.55, \xi = 0.1, \omega = 1, t = 1, \theta_a = 1.$ 





Graph for the Temperature with increasing values of Heat SourceH when  $\alpha = 1$ , R =  $0.55, M = 1.5, \xi = 0.1, \omega = 1, t = 1, \theta_a = 1$ 

#### VII. Conclusion

This study has analyzed theoretically the effect of heat source, slip, pulsatilepressure of the blood flow and body acceleration on non-Newtonian steady and unsteady blood flowing through a stenotic artery with stenosis and permeable walls. The summary of the results from the study showed that,

The body acceleration Go increase caused an increase in the velocity of the blood, flow blood (i) acceleration, shear stress at the stenotic artery wall and the volumetric flow rate. Hypertensive patients are encouraged minimize their movement by land, air and water, minimize activities with stress which could increase the work rate of the heart leading to cardiac arrest. Increased body acceleration could improve patient's health with hypotension.

(ii) The increase in the heat source caused the blood viscosity to reduce hence increasing the velocity, acceleration and volumetric flow rate of the blood while there was a reduced effect on the shear stress at the artery walls with stenosis.

(iii) Increased inclination artery presults to an increase in the velocity of the blood flow velocity, shear stress and the volumetric flow rate at the artery wall with stenosis but a fluctuating pattern in the acceleration of the blood.

(iv) The permeability of the porous wall k increase, caused an increase in the velocity and acceleration of the blood flow, shear stress at the stenotic artery wall and volumetric flow rate.

(v) Magnetic field M increase caused a decrease in the velocity and acceleration of the blood flow, shear stress at the stenotic artery wall and volumetric flow rate. Health practitioners could adopt this in treatment of patients with hypertension with the use of a magnetic jacket that will aid the decrease in the flow of blood to the body muscles from the heart.

(vi) Pulsatile pressure Pl increase causes an increase in the velocity and acceleration of the blood flow, shear stress at the stenotic artery wall and volumetric flow rate. The heart when overworked will pump more blood to muscles in the body pressure is increased. Hence a lot of rest could be recommended to patients with high blood pressure (hypertension).

(vii) Increase in slip h induced at the artery wall with stenosis, decreases the velocity, acceleration and volumetric flow rate of the blood flow but decreases the shear stress at the stenotic artery wall. This could be adopted to treat hypertensive patients when injected drug induces a slip at the wall of the stenotic artery. This could help in treatment of heart disease by cleaning the heart valves and cavities such that the reduction in the radius stenosis will cause the increase of velocity, acceleration and volumetric flow rate of the blood and a reduced effect in the shear stress at the wall.

Conclusively, this study could be of immense benefit to the medical and health practitioners when administering treatment to patients because of the prediction of the outcome of the study shown in the results.

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# APPENDIX

$$L_{4} = \frac{G_{r}C_{2}\alpha_{1}^{4}}{\beta_{2}2^{2}4^{2}6^{2}8^{2}}; L_{3} = \frac{1}{\beta_{2}} \left( 64L_{4} - \frac{G_{r}C_{2}\alpha_{1}^{3}}{2^{2}4^{2}6^{2}} \right); L_{2} = \frac{1}{\beta_{2}} \left( 36L_{3} + \frac{G_{r}C_{2}\alpha_{1}^{2}}{2^{2}4^{2}} \right); L_{1} = \frac{1}{\beta_{2}} \left( 16L_{2} - \frac{G_{r}C_{2}\alpha_{1}}{2^{2}} \right); L_{1} = \frac{1}{\beta_{2}} \left( 16L_{2} - \frac{G_{r}C_{2}\alpha_{1}}{2^{2}} \right); L_{2} = \frac{1}{\beta_{2}} \left( 16L_{2} - \frac{G_{r}C_{2}\alpha_{1}}{2^{2}} \right); M_{2} = \frac{1}{\beta_{1}} \left( 36M_{3} + \frac{G_{r}C_{1}N^{4}}{2^{2}4^{2}} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{0} = \frac{1}{\beta_{1}} \left( 4M_{1} + G + G_{r}C_{1} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{0} = \frac{1}{\beta_{1}} \left( 4M_{1} + G + G_{r}C_{1} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{0} = \frac{1}{\beta_{1}} \left( 4M_{1} + G + G_{r}C_{1} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{0} = \frac{1}{\beta_{1}} \left( 4M_{1} + G + G_{r}C_{1} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{1} + \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{2} - \frac{G_{r}C_{1}N^{2}}{2^{2}} \right); M_{1} = \frac{1}{\beta_{1}} \left( 16M_{1} + \frac{G_{r}C_{1}N^{2}}{$$

E. Omamoke, et. al. "Slip and Pulsatile Mhd Blood Flow Through An Inclined Stenosed Artery With Body Acceleration And Heat Source Effects." *IOSR Journal of Mathematics (IOSR-JM)*, 18(1), (2022): pp. 01-23.