

Fixed Point Theorems For Generalized Contraction In Ultra Metric Spaces

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Abstract: In this paper, we prove some fixed point theorems for two and three maps of Jungck generalized contractive mappings on spherically complete Ultra metric space using generalized contractive mappings. Our results extend various known results in ultra metric space such as Pant and Mishra [13], Gajic [7] and others.

I. Introduction

Generalization of metric space have been done in many ways such as 2-metric space, G- metric space, b- metric space, probabilistic metric space, Fuzymetric space etc. Rooji [1] introduced the concept of ultrametric space. Later on Petals and Vidalis [2] proved a fixed point theorem for contractive mappings on spherically complete ultrametric space X.

Petals and Vidalis [2] established the following fixed point theorem:

Theorem (1.1): Let (X,d) be a spherically complete ultrametric space and $T:X \rightarrow X$ a contractive mapping. Then T has a unique fixed point.

In 2001 Gajic [7] obtained the following generalization of the above theorem:

Theorem (1.2): Let (X,d) be a spherically complete ultrametric space and $T:X \rightarrow X$ a mapping such that for all $x,y \in X, x \neq y$,

$$d(Tx, Ty) < \max \{ d(x,y), d(x,Tx), d(y,Ty) \}$$

Then T has a unique fixed point.

Later on Rao and Kishore [5] extended the above result for a pair of maps of Jungck type as follows:

Theorem (1.3): Let (X,d) be a spherically complete ultrametric space. If f and T are self maps on X satisfying

$$T(X) \subseteq f(X)$$

$$d(Tx, Ty) < \max \{ d(f(x), f(y)), d(f(x), T(x)), d(f(y), T(y)) \}, \quad x, y \in X, x \neq y.$$

then there exists $z \in X$ such that $fz = Tz$.

Further if f and T are coincidentally commutating at z then z is the unique common fixed point of f and T.

Further in 2014, Mishra and Pant [13] extended the result of Gajic [7] by introducing a more generalized contractive mapping as follows:

Definition (1.4): A self-mapping T of a metric (resp. an ultrametric) space X is said to be generalized contractive mapping if

$$d(Tx, Ty) < M(x,y) \text{ for all } x,y \in X \text{ with } x \neq y, \text{ where}$$

$$M(x,y) = \max \{ d(x,y), d(x,Tx), d(y,Ty), d(x,Ty), d(y,Tx) \}$$

and proved the following theorem:

Theorem (1.5): Let (X,d) be a spherically complete ultrametric space and $T:X \rightarrow X$ a generalized contractive mapping. Then T has a unique fixed point.

In this paper we have generalized and extended the previous results by:

- (i) Increasing the number of maps.
- (ii) Increasing the number of terms in R.H.S.

II. Preliminaries

Definition (2.1): An ultrametric space is a set X together with a function $d: X \times X \rightarrow \mathbb{R}_+$, which satisfies for all x,y and z in X

$$(U_1) d(x,y) \geq 0$$

$$(U_2) d(x,y) = 0 \text{ if } x=y$$

$$(U_3) d(x,y) = d(y,x) \text{ (Symmetry)}$$

$$(U_4) d(x,z) \leq \max \{ d(x,y), d(y,z) \} \text{ (strong triangle or ultrametric inequality)}$$

Example (2.2): The discrete metric is an ultrametric.

Example (2.3): the p-adic number form a complete ultrametric space.

Definition (2.4): An ultrametric space (X,d) is said to be spherically complete if every shrinking collection of balls in X has non-empty intersection.

Definition (2.5): A self mapping T of a metric (resp. an ultrametric) space X is said to be contractive (or, strictly contractive) mapping if

$$d(Tx,Ty) < d(x,y) \text{ for all } x,y \in X \text{ with } x \neq y.$$

Example (2.6): Let $X = (-\infty, \infty)$ endowed with the usual metric and $T: X \rightarrow X$ defined by

$$Tx = x + \frac{1}{1 + e^x}$$

for all $x \in X$. Here X is complete and T is a contractive mapping but T does not have a fixed point.

Definition (2.7): A self – mapping T of a metric (resp. an ultrametric) space X is said to be generalised contractive mapping if:

$$d(Tx,Ty) < M(x,y) \text{ for all } x,y \in X \text{ with } x \neq y, \text{ where}$$

$$M(x,y) = \max \{d(x,y), d(x,Tx), d(y,Ty), d(x,Ty), d(y,Tx)\}$$

Definition (2.8): For $x \in X, r > 0, B_r(x) = \{y \in X : d(x,y) < r\}$ is called the ball (open) with centre x and radius r .

III. Main Results

Theorem (3.1): Let (X,d) be a spherically complete ultrametric space. Let f and T are self maps on X satisfying:

1. $T(x) \subseteq f(x)$

2. $d(Tx,Ty) < \max \{d(f(x),f(y)), d(f(x),T(x)), d(f(y),T(y)), d(f(x),T(y)), d(f(y),T(x))\} \quad \forall x,y \in X, x \neq y.$

then there exists $z \in X$ such that $f(z) = T(z)$.

Further if f and T are coincidentally commutating at z then z is the unique common fixed point of f and T .

Proof:

Let $B_a = \{x : d(x,fa) \leq d(fa,Ta)\}$ denote the closed sphere centred at fa with the radius $d(fa,Ta)$ and let A be the collection of these spheres for all $a \in X$. Then the relation $B_a \leq B_b$ if $B_b \subseteq B_a$ is a partial order on A . Let A_1 be a totally ordered sub family of A . Since (X,d) is spherically complete, we have $\bigcap_{B_a \in A_1} B_a \neq \emptyset$

Let $f(b) \in B_a$ and $B_a \in A_1$. Then $f(b) \in B_a$. Hence

$$d(f(b),f(a)) \leq d(f(a),T(a)) \dots\dots\dots (i)$$

If $a=b$, then $B_a=B_b$. We assume that $a \neq b$.

Let $x \in B_b$, then

$$\begin{aligned} d(x,f(b)) &\leq d(f(b),T(b)) \\ &\leq \max \{d(f(b),f(a)), d(f(a),T(a)), d(T(a),T(b))\} \\ &= \max \{d(f(a),T(a)), d(Ta,Tb)\} \dots\dots\dots \text{from (i)} \\ &< \max \{d(f(a),T(a)), d(f(a),f(b)), d(f(b),T(b)), d(f(a),T(b)), d(f(b),T(a))\} \text{ from (2)} \\ &< d(f(a),T(a)) \dots\dots\dots (ii) \end{aligned}$$

Now, $d(x,f(a)) \leq \max \{d(x,f(b)), d(f(b),f(a))\} \leq d(f(a),T(a))$ from (i) & (ii)

Thus, $x \in B_a$. Hence $B_b \subseteq B_a$ for any $B_a \in A_1$. Thus B_b is an upper bound in A and hence by Zorn's Lemma, A has a maximal element say $B_z, z \in X$.

Suppose that $f(z) \neq T(z)$. Since $Tz \in T(x) \subseteq f(x)$, there exists $w \in X$ such that $T(z) = f(w)$. clearly $z \neq w$. Now from (2) we have:

$$\begin{aligned} d(f(w),T(w)) &= d(Tz,Tw) \\ &< \max \{d(f(z),f(w)), d(f(z),T(z)), d(f(w),T(w)), d(f(z),T(w)), d(f(w),T(z))\} \end{aligned}$$

But by the strong triangle inequality, we have

$$\begin{aligned} d(f(z),T(w)) &< \max \{d(f(z),T(z)), d(f(w),T(w))\} \\ \text{and } d(f(w),T(z)) &< \max \{d(f(w),T(z)), d(f(z),T(z))\} \end{aligned}$$

$$\begin{aligned} \text{Thus, } d(f(w),T(w)) &= d(T(z),T(w)) \\ &< \max \{d(f(z),f(w)), d(f(z),T(z)), d(f(w),T(w))\} \\ &= d(f(z),f(w)). \end{aligned}$$

Thus $fz \notin B_w$. Hence $fz \notin B_w$. And this contradicts the maximality of B_z . Hence $f(z) = T(z)$.

Further assume that f and T are coincidentally commutating at z .

$$\text{Then } f^2(z) = f(f(z)) = f(T(z)) = Tf(z) = T(T(z)) = T^2(z)$$

Suppose that $f(z) \neq z$. Now from (2) we have,

$$\begin{aligned} d(Tf(z),T(z)) &< \max \{d(f^2(z),f(z)), d(f^2(z),Tf(z)), d(f(z),T(z)), d(f^2(z),T(z)), d(f(z),Tf(z))\} \\ &= d(Tf(z),T(z)) \end{aligned}$$

Hence, $f(z) = z$. Thus $z = f(z) = T(z)$

Uniqueness: Suppose (if possible) w is another common fixed point of f and T such that $z \neq w$.

$$\text{Then } d(z,w) = d(T(z),T(w))$$

$$< \max \{d(f(z),f(w)), d(f(z),T(z)), d(f(w),T(w)), d(f(z),T(w)), d(f(w),T(z))\}$$

$$= \max\{d(z,w), d(z,z), d(w,w)\}$$

$= d(z,w)$, which is not possible. Thus our supposition is wrong and hence z is the unique common fixed point of f and T .

Remarks (3.2): If we put $f=I$, (identity map) theorem (1.1.6) follows.

Example (3.3): Let $X=R$, and $d(x, y) = \begin{cases} 0 & \text{if } x = y \\ 1 & \text{if } x \neq y \end{cases}$

We define $T, f : X \rightarrow X$ as $Tx=1$ and $f(x) = \frac{x+1}{2} \forall x \in X$.

Then all conditions of theorem (1.3.6) are satisfied and 1 is the unique common fixed point of T and f .

Theorem (3.4): Let (X,d) be a spherically complete Ultra metric space. If $S, T: X \rightarrow X$ are mappings such that:

- (i) $d(Tx, Ty) < \max\{d(Sx, Sy), d(Sx, TSx), d(Sy, TSy), d(Sx, TSy), d(Sy, TSx)\} \forall x, y \in X, x \neq y$
- (ii) $d(Sx, Sy) < d(x, y)$
- (iii) $TS(x) = ST(x) \forall x \in X$

Then S and T have a unique common fixed point in X .

Proof: Using conditions (ii) and (iii) in (i) we have

$$d(Tx, Ty) < \max\{d(Sx, Sy), d(Sx, STx), d(Sy, STy), d(Sx, STy), d(Sy, STx)\}$$

$$\text{or } d(Tx, Ty) < \max\{d(x, y), d(x, Tx), d(y, Ty), d(x, Ty), d(y, Tx)\}$$

By theorem (1.5) T has unique fixed point i.e. there exists a point $z \in X$ such that $z = Tz$.

Now,

$$\begin{aligned} d(z, Sz) &= d(Tz, STz) = d(Tz, TSz) \\ &< \max\{d(Sz, S^2z), d(S^2z, TS^2z), d(S^2z, TS^2z), d(S^2z, TS^2z), d(S^2z, TS^2z)\} \\ &= \max\{d(Sz, S^2z), d(S^2z, S^2Tz), d(S^2z, S^2Tz), d(S^2z, S^2Tz), d(S^2z, S^2Tz)\} \\ &< \max\{d(z, Sz), d(Sz, Sz), d(Sz, Sz), d(Sz, Sz), d(Sz, Sz)\} \end{aligned}$$

i.e. $d(z, Sz) < d(z, Sz)$ which is a contradiction. Hence $z = Sz$.

Uniqueness: If possible let z and w be two distinct fixed point of S and T . Then,

$$\begin{aligned} d(z, w) &= d(Tz, Tw) < \max\{d(Sz, Sw), d(Sz, TS(w)), d(Sz, TS(w)), d(Sz, TS(w)), d(Sw, TS(z))\} \\ &= \max\{d(z, w), d(z, w), d(z, w), d(z, w), d(w, z)\} \end{aligned}$$

i.e. $d(z, w) < d(z, w)$ which is not possible and hence $z = w$. Therefore z is the unique common fixed point of S and T .

Remarks (3.5): If we put $S=I$ (identity map), theorem (3.5) reduces to the theorem (1.6) due to Mishra and Pant[13].

Theorem (3.6): Let (X,d) be spherically complete ultrametric space. If T, f and g are self maps on X satisfying

- (i) $g(x) \subseteq f(x)$
- (ii) $d(g(x), g(y)) < \max\{d(fT(x), fT(y)), d(fT(x), gT(x)), d(fT(y), gT(y)), d(fT(x), gT(y)), d(fT(y), gT(x))\} \forall x, y \in X, x \neq y$
- (iii) $d(Tx, Ty) < d(x, y)$
- (iv) $Tf(x) = fT(x)$ and $Tg(x) = gT(x)$ then $z = Tz = f(z) = g(z)$. further

Proof: using condition (iii) and (iv) condition (i) becomes:

$$d(g(x), g(y)) < \max\{d(Tf(x), Tf(y)), d(Tf(x), Tg(x)), d(Tf(y), Tg(y)), d(Tf(y), Tg(x))\} \forall x, y \in X$$

$$\text{or, } d(g(x), g(y)) < \max\{d(f(x), f(y)), d(f(x), g(x)), d(f(y), g(y)), d(f(x), g(y)), d(f(y), g(x))\}$$

By theorem (1.5) there exists a unique common fixed point for f and g i.e. $z = f(z) = g(z)$.

Now

$$\begin{aligned} d(z, Tz) &= d(g(z), Tg(z)) = d(g(z), gT(z)) \\ &< \max\{d(fT(z), fT^2(z)), d(fT(z), gT(z)), d(fT^2(z), gT^2(z)), d(fT(z), gT^2(z)), d(fT^2(z), gT(z))\} \\ &< \max\{d(f(z), Tf(z)), d(f(z), g(z)), d(Tf(z), Tg(z)), d(f(z), Tg(z)), d(Tf(z), g(z))\} \\ &= \max\{d(z, Tz), d(z, z), d(Tz, Tz), d(z, Tz), d(Tz, z)\} \end{aligned}$$

i.e. $d(z, Tz) < d(z, Tz)$ which is a contradiction, hence $z = Tz$ and using the theorem (1.6), z is unique for T . Hence, T, f and g have a unique common fixed point.

Remarks (3.7): If we put $T = I$, identity map, theorem (3.6) reduces to the theorem (3.5).

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