

On M_n^{**} -Manifold

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Abstract: In the present paper, after defining an integrated contact metric structure manifold [3] I have defined M_n^{**} and nearly M_n^{**} manifold. It has been shown that M_n^{**} is integrable. Several useful theorems on these manifolds have also been derived.

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I. Introduction

Let M_n be a differentiable manifold of differentiability class C^∞ . Let there exist in M_n a vector valued C^∞ -linear function Φ , a C^∞ -vector field η and a C^∞ -one form ξ such that

$$(1.1) \quad \Phi^2(X) = a^2X - c\xi(X)\eta$$

$$(1.2) \quad (\bar{\eta}) = 0,$$

$$(1.3) \quad G(\bar{X}, \bar{Y}) = a^2G(X, Y) - c\xi(X)\xi(Y)$$

Where $\Phi(X) = \bar{X}$, a is a nonzero complex number and c is an integer.

Let us agree to say that Φ gives to M_n a differentiable structure define by algebraic equation (1.1). We shall call (Φ, η, a, c, ξ) as an integrated contact structure.

Remark 1.1: The manifold M_n equipped with an integrated contact structure (Φ, η, a, c, ξ) will be called an integrated contact structure manifold.

Remark 1.2: The C^∞ manifold M_n satisfying (1.1), (1.2) and (1.3) is called an integrated contact metric structure manifold $(\Phi, \eta, a, c, G, \xi)$

Agreement 1.1: All the equations which follow will hold for arbitrary vector field X, Y, Z, \dots etc.

It is easy to calculate in M_n that

$$(1.4) \quad \xi(\eta) = \frac{a^2}{c}$$

$$(1.5) \quad \Phi(\bar{X}) = 0$$

and

$$(1.6) \quad G(X, \eta) \underline{\underline{def}} \xi(X)$$

Remark 1.3: The integrated contact metric structure manifold $(\Phi, \eta, a, c, G, \xi)$ gives an almost Norden contact metric manifold [2], Lorentzian Para-contact manifold [1] or an almost Para-contact Riemannian manifold [4] according as $(a^2 = -1, c = 1)$, $(a^2 = 1, c = -1)$ or $(a^2 = 1, c = 1)$

Agreement 1.2: An integrated contact metric structure manifold will be denoted by M_n .

In the sequel, arbitrary vector fields will be denoted by X, Y, Z, \dots etc.

Definition 1.1: A C^∞ -manifold M_n satisfying

$$(1.7) \quad \bar{X} = D_X \eta$$

will be denoted by M_n^* . It is easy to calculate in M_n^*

$$(1.8) \quad (D_X \xi)(Y) = \Phi(X, Y),$$

where

$$(1.9) \quad \Phi(X, Y) \stackrel{\text{def}}{=} G(\bar{X}, Y) = G(X, \bar{Y})$$

$$(1.10) \quad (D_X \xi)(Y) - (D_Y \xi)(X) = 0$$

Definition 1.2: A C^∞ -manifold M_n^* satisfying

$$(1.11) \quad (D_X \xi)(\bar{Y}) = -(D_{\bar{X}} \xi)(Y) = -(D_Y \xi)(\bar{X}); \quad D_n \Phi = 0$$

will be called M_n^{**} -manifold if

$$(1.12) \quad (D_X \Phi)(Y) = -\xi(Y)(D_{\bar{X}} \eta) + (D_Y \xi)(\bar{X})\eta$$

and will be called nearly M_n^{**} -manifold if

$$(1.13) \quad (D_X \Phi)(Y) + (D_Y \Phi)(X) = -\xi(Y)D_{\bar{X}} \eta - \xi(X)D_{\bar{Y}} \eta$$

where D is a Riemannian connection.

The Nijenhuis tensor N with respect to Φ is given by

$$(1.14) \quad N(X, Y) \stackrel{\text{def}}{=} [\bar{X}, \bar{Y}] + \overline{[X, Y]} - \overline{[\bar{X}, Y]} - \overline{[X, \bar{Y}]}$$

which yields

$$(1.15) \quad N(X, Y) = (D_{\bar{X}} \Phi)(Y) - (D_{\bar{Y}} \Phi)(X) - \overline{(D_X \Phi)(Y)} + \overline{(D_Y \Phi)(X)}$$

and

$$(1.16) \quad \begin{aligned} \Phi(N(X, Y, Z)) &= (D_{\bar{X}} \Phi)(Y, Z) - (D_{\bar{Y}} \Phi)(X, Z) \\ &\quad - (D_X \Phi)(Y, Z) + (D_Y \Phi)(X, Z) \end{aligned}$$

where

$$(1.17) \quad \Phi(N(X, Y, Z)) \stackrel{\text{def}}{=} G(N(X, Y), Z)$$

II. On M_n^{**} -Manifold

Theorem 2.1: In M_n^* , we have

$$(2.1a) \quad (D_X \Phi)(Y, Z) = -\xi(Y) \Phi(\bar{X}, Z) + (D_Y \xi)(\bar{X}) \xi(Z)$$

$$(2.1b) \quad \begin{aligned} (D_X \Phi)(Y, Z) + (D_Y \Phi)(X, Z) &= a^2 [\xi(Y)G(X, Z) + \xi(X)G(Y, Z)] \\ &\quad + 2c \xi(X) \xi(Y) \xi(Z) \end{aligned}$$

$$(2.1c) \quad (D_X \Phi)(\bar{Y}, Z) + (D_Y \Phi)(Y, \bar{Z}) = [(D_{\bar{Y}} \xi)(\bar{X}) \xi(Z) + a^2 \xi(Y) \Phi(X, Z)]$$

Proof: (1.9) yields

$$(2.2) \quad (D_X \Phi)(Y, Z) = G((D_X \Phi)(Y), Z)$$

Operating G on both sides of (1.12) and using (1.3) (1.6) and (2.2), we get

$$(2.3) \quad (D_X \Phi)(Y, Z) = -\xi(Y)G(D_{\bar{X}} \eta, Z) + (D_Y \xi)(\bar{X}) \xi(Z)$$

Using (1.7) and (1.9) in the above equation, we get (2.1a). Using (1.9) and (1.1) in (2.1a), we get

$$(2.4) \quad (D_X \cdot \Phi)(Y, Z) = a^2 \xi(Y) G(X, Z) + c \xi(X) \xi(Y) \xi(Z) + (D_Y \xi)(\bar{X}) \xi(Z)$$

Interchanging X and Y in above equation, we get

$$(2.5) \quad (D_Y \cdot \Phi)(X, Z) = a^2 \xi(X) G(Y, Z) + c \xi(Y) \xi(X) \xi(Z) + (D_X \xi)(\bar{Y}) \xi(Z)$$

adding (2.4) and (2.5) and using (1.11), we get (2.1b). Barring Y in (2.4) and using (1.5), we get

$$(2.6) \quad (D_X \cdot \Phi)(\bar{Y}, Z) = (D_{\bar{Y}} \xi)(\bar{X}) \xi(Z)$$

Barring Z in (2.4) and using (1.5) and (1.9), we get

$$(2.7) \quad (D_X \cdot \Phi)(Y, \bar{Z}) = a^2 \xi(Y) \cdot \Phi(X, Z)$$

adding (2.6) and (2.7), we get (2.1c).

Corollary 2.1: In M_n^{**} , we have

$$(2.8a) \quad (D_X \cdot \Phi)(Y, \bar{Z}) = -a^2 \xi(Y) \cdot \Phi(X, Z)$$

$$(2.8b) \quad (D_X \cdot \Phi)(\bar{Y}, \bar{Z}) = 0$$

$$(2.8c) \quad (D_{\bar{X}} \cdot \Phi)(Y, Z) + (D_Y \cdot \Phi)(\bar{X}, Z) - (D_X \cdot \Phi)(Y, \bar{Z}) = 0$$

$$(2.8d) \quad (D_{\bar{X}} \cdot \Phi)(\bar{Y}, Z) + (D_{\bar{Y}} \cdot \Phi)(\bar{X}, Z) = 0$$

Proof: Barring Z in (2.1a) and using (1.5), (1.9), (1.1), (1.3), we get (2.8a). Barring Y in (2.8a) and using (1.5), we get (2.8b). Barring X in (2.1b) and using (1.5) and (2.8a), we get (2.8c). Barring X and Y both in (2.1b) and using (1.5), we get (2.8d).

Theorem 2.2: M_n^{**} is integrable.

Proof: Barring X in (1.12), we get

$$(2.9) \quad (D_{\bar{X}} \Phi)(Y) = -\xi(Y) (D_{\bar{X}} \eta) + (D_Y \xi)(\bar{X}) \eta$$

Barring both sides of (1.12) and using (1.2), we get

$$(2.10) \quad \overline{(D_X \Phi)(Y)} = -\xi(Y) \overline{(D_{\bar{X}} \eta)}$$

Interchanging X and Y in (2.9) and (2.10) separately, we get

$$(2.11) \quad (D_{\bar{Y}} \Phi)(X) = -\xi(X) (D_{\bar{Y}} \eta) + (D_X \xi)(\bar{Y}) \eta,$$

and

$$(2.12) \quad \overline{(D_Y \Phi)(X)} = -\xi(X) \overline{(D_{\bar{Y}} \eta)}$$

Using (2.9), (2.10), (2.11), (2.12) and (1.7) in (1.15), we get

$$(2.13) \quad N(X, Y) = \left[(D_Y \xi)(\bar{X}) - (D_X \xi)(\bar{Y}) \right] \eta$$

(1.1) yields

$$(2.14) \quad \xi(\bar{Y}) = \xi(a^2 Y - c \xi(Y) \eta)$$

Differentiating corollary (2.14) covariantly along the vector X and using (1.4), we get

$$(2.15) \quad (D_X \xi)(\bar{Y}) = a^2 (D_X \xi)(Y)$$

Integrating X and Y in the above equation, we get

$$(2.16) \quad (D_Y \xi)(\bar{X}) = a^2 (D_Y \xi)(X)$$

Using (2.15), (2.16) and (1.10) in (2.13), we get

$$(2.17) \quad N(X, Y) = 0$$

which proves the theorem.

Corollary 2.2: In M_n^{**} , we have

$$(2.18) \quad (D_X \Phi)(Y) = -a^2 \xi(Y)X + c\xi(X)\xi(Y)\eta + (D_Y \xi)(\bar{X})\eta$$

$$(2.19) \quad c\xi((D_X \Phi)(Y)) = -a^2 (D_Y \xi)(\bar{X})$$

$$(2.20) \quad \mathcal{N}(X, Y, Z) = 0$$

Proof: Using (1.7) and (1.1) in (1.12), we get (2.18). Operating ξ on both the sides of (2.18) and using (1.4), we get (2.19). Operating G on both the sides of (2.17) and using (1.17), we get (2.20).

III. Affine Connection

Let B be an affine connection in M_n^{**} defined by

$$(3.1) \quad B_X Y \underline{\underline{def}} D_X Y + H(X, Y)$$

where $H(X, Y)$ is a vector valued bilinear function. If S be the torsion tensor of the connection B , we have

$$(3.2) \quad S(X, Y) = H(X, Y) - H(Y, X)$$

If $H(X, Y)$ is skew-symmetric, we have

$$(3.3) \quad S(X, Y) = 2H(X, Y) = -2H(Y, X)$$

Consequently

$$(3.4) \quad \mathcal{S}(X, Y, Z) = 2 \mathcal{H}(X, Y, Z) = -2 \mathcal{H}(Y, X, Z),$$

where

$$(3.5a) \quad \mathcal{S}(X, Y, Z) \underline{\underline{def}} G(S(X, Y), Z),$$

and

$$(3.5b) \quad \mathcal{H}(X, Y, Z) \underline{\underline{def}} G(H(X, Y), Z)$$

Theorem 3.1: On M_n^{**} , we have

$$(3.6) \quad (B_X \Phi)(Y) + \xi(Y)(B_{\bar{X}}\eta) - (B_Y \xi)(\bar{X})\eta = H(X, \bar{Y}) - \overline{H(X, Y)} \\ + \xi(Y)H(\bar{X}, \eta) + \xi(H(Y, \bar{X}))\eta$$

Proof: Using (1.5) in (1.12) and $\Phi(X) = \bar{X}$, we get

$$(3.7) \quad D_X \bar{Y} - \overline{D_X Y} = -\xi(Y)(D_{\bar{X}}\eta) - \xi(D_Y \bar{X})\eta$$

Using (3.1) in the above, we get (3.6).

Theorem 3.2: On M_n^{**} , we have

$$(3.8) \quad (B_X \xi)(\bar{Y}) = -(B_{\bar{X}} \xi)(Y) = -(B_Y \xi)(\bar{X}),$$

if

$$(3.9a) \quad \xi(H(X, \bar{Y})) = 0,$$

and

$$(3.9b) \quad H(X, Y) \text{ is skew-symmetric}$$

Proof: Using (1.5) in (1.11), we have

$$\xi(D_X \bar{Y}) = -\xi(D_Y \bar{X})$$

Using (3.1) in the above equation, we get

$$(3.10) \quad \xi(B_X \bar{Y}) + \xi(B_Y \bar{X}) = \xi(H(X, \bar{Y})) + \xi(H(Y, \bar{X}))$$

From (3.9b), we have

$$(3.11) \quad \xi(H(\bar{X}, Y)) = -\xi(H(Y, \bar{X}))$$

From (1.5), we get

$$(3.12) \quad \xi(B_X \bar{Y}) = -(B_X \xi)(\bar{Y})$$

From (3.10), (3.11) and (3.12), we get

$$(3.13) \quad (B_X \xi)(\bar{Y}) + (B_Y \xi)(\bar{X}) = -\xi(H(X, \bar{Y})) + \xi(H(\bar{X}, Y))$$

(1.11) yields

$$(3.14) \quad \xi(D_X \bar{Y}) = \bar{X} \xi(Y) - \xi(D_X Y)$$

Using (3.1) in above, we get

$$(3.15) \quad (B_X \xi)(\bar{Y}) + (B_{\bar{X}} \xi)(Y) = -\xi(H(X, \bar{Y})) - \xi(H(\bar{X}, Y))$$

Thus using (3.9a), (3.9b) in (3.13) and (3.15), we get (3.8).

Theorem 3.3: On M_n^{**} , we have

$$(3.16) \quad \xi(B_X \bar{Y}) + \xi(B_{\bar{X}} \bar{Y}) = \xi(H(\bar{X}, \bar{Y})) + a^2 \xi(H(X, Y)) - c \xi(Y) \xi(H(X, \eta))$$

Proof: (1.11) yields

$$\xi(D_X \bar{Y}) = \bar{X} (\xi(Y)) - \xi(D_{\bar{X}} Y)$$

Using (3.1) in the above equation, we get

$$\xi(D_X \bar{Y}) + \xi(B_{\bar{X}} Y) = \bar{X} (\xi(Y)) + \xi(H(X, \bar{Y})) + \xi(H(\bar{X}, Y))$$

Barring Y in the above equation and using (1.1), (1.2), we get (3.16).

Theorem 3.4: In M_n^{**} , we have

$$(3.17) \quad (D_X \cdot \Phi)(Y, Z) + (D_Y \cdot \Phi)(Z, X) + (D_Z \cdot \Phi)(X, Y) = 2[\xi(X)(D_X \xi)(\bar{Y}) + \xi(Y)(D_X \xi)(\bar{Z}) + \xi(Z)(D_Y \xi)(\bar{X})]$$

Proof: From (1.7), (1.8) and (1.9), we have

$$(3.18) \quad (D_X \xi)(Y) = G(D_X \eta, Y)$$

Barring X in (3.18), we get

$$(3.19) \quad (D_{\bar{X}} \xi)(Y) = G(D_{\bar{X}} \eta, Y)$$

Using (3.19) in (2.3), we get

$$(3.20) \quad (D_X \cdot \Phi)(Y, Z) = -\xi(Y)(D_{\bar{X}} \xi)(Z) + (D_Y \xi)(\bar{X}) \xi(Z)$$

By the cyclic permutation of X, Y, Z , we also have

$$(3.21) \quad (D_Y \cdot \Phi)(Z, X) = -\xi(Z)(D_{\bar{Y}} \xi)(X) + (D_Z \xi)(\bar{Y}) \xi(X)$$

$$(3.22) \quad (D_Z \cdot \Phi)(X, Y) = -\xi(X)(D_{\bar{Z}} \xi)(Y) + (D_X \xi)(\bar{Z}) \xi(Y)$$

adding (3.20), (3.21) and (3.22) and using (1.11), we get (3.17).

Theorem 3.5: M_n^{**} is necessarily nearly M_n^{**} .

Proof: In M_n^{**} , we have a result (3.21). Interchanging X and Z in (3.21), we get

$$(3.23) \quad (D_Y \cdot \Phi)(X, Z) = -\xi(X)((D_{\bar{Y}}\xi)(Z)) + (D_X\xi)(\bar{Y})\xi(Z)$$

adding (3.20) and (3.23) and using (1.11), we get

$$(3.24) \quad (D_X \cdot \Phi)(Y, Z) + (D_Y \cdot \Phi)(X, Z) = -\xi(Y)(D_{\bar{X}}\xi)(Z) - \xi(X)(D_{\bar{Y}}\xi)(Z)$$

Using (2.2) and (3.19) in the above equation, we get

$$G((D_X\Phi)Y, Z) + G((D_Y\Phi)X, Z) = -\xi(Y)G(D_{\bar{X}}\eta, Z) - \xi(X)G(D_{\bar{Y}}\eta, Z)$$

which yield (1.13). Hence M_n^{**} is necessarily nearly M_n^{**} .

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